

① Examples of Linear Models

② Linear Algebra :
- Vector space
- Projection

+ LSE

③ Estimability, Imposing Conditions

④ Gauss Markov -

Linear Algebra : Spectral decomposition of square, symmetric positive definite matrix

$$\text{Cov}(e) = \sigma^2 V$$

• HW#1 & #2 w/ solutions

• HW#3

• Exam 1: 04/26 (Tue)

$$-\frac{1}{2} (x - \mu)^T (\Sigma^{-1}) (x - \mu)$$

♣ Def: A quadratic form in the n variables is $\mathbf{x}^T \mathbf{A} \mathbf{x}$ where n -dim vector \mathbf{x} and \mathbf{A} is a $n \times n$ symmetric matrix.

Observe

$$\mathbf{x}^T \mathbf{A} \mathbf{x} = \sum_{ij} a_{ij} x_i x_j,$$

that is, it has only squared terms x_i^2 and product terms, $x_i x_j$.

† Th: A symmetric matrix \mathbf{A} is positive (nonnegative) definite if, for any nonzero vector $\mathbf{v} \in \mathbb{R}^n$, $\mathbf{v}^T \mathbf{A} \mathbf{v}$ is positive (nonnegative).

$$\begin{aligned} 0 &\leq \mathbf{x}^T \mathbf{A} \mathbf{x} && \text{for all } \mathbf{x}, \\ 0 &< \mathbf{x}^T \mathbf{A} \mathbf{x} && \text{for all } \mathbf{x} (\neq \mathbf{0}). \end{aligned}$$

① Let $\mathbf{A} = \mathbf{I}$

$$\mathbf{x}^T \mathbf{I} \mathbf{x} = x_1^2 + \dots + x_n^2 > 0 \text{ for all } \mathbf{x} (\mathbf{x} \neq \mathbf{0})$$

\mathbf{I} : p.d

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② Let $\mathbf{A} = \mathbf{J}_{n \times n} = \begin{matrix} \mathbf{1}_n & \mathbf{1}_n^T \\ \mathbf{1}_n & \mathbf{1}_n^T \end{matrix}$ ② $\mathbf{z}^T \mathbf{z} = z^2$

$$\mathbf{x}^T \mathbf{J} \mathbf{x} = \mathbf{x}^T \mathbf{1}_n \mathbf{1}_n^T \mathbf{x} = \underbrace{(\mathbf{1}_n^T \mathbf{x})}_{(x_1 + \dots + x_n)}^T (\mathbf{1}_n^T \mathbf{x}) = (x_1 + \dots + x_n)^2 \geq 0$$

for any \mathbf{x} ,

$$\mathbf{x} = [1, \dots, 1]^T \Rightarrow \mathbf{x}^T \mathbf{J} \mathbf{x} = 0$$

$\Rightarrow \mathbf{J}$: nonnegative definite

- Let's connect the spectral decomposition of a symmetric matrix \mathbf{A} into \mathbf{A}^{-1} .

$$\Lambda = \begin{bmatrix} \lambda & 0 \\ 0 & 0 \end{bmatrix} \quad \Lambda^{-1} = \begin{bmatrix} 1/\lambda & 0 \\ 0 & 0 \end{bmatrix}$$

From the previous slide,

$$\mathbf{A}^{-1} = \mathbf{Q} \Lambda^{-1} \mathbf{Q}^T$$

where Λ is the diagonal matrix with λ_j .

† Th: Let \mathbf{A} be a $n \times n$ symmetric matrix of rank r ($r \leq n$). Let Λ_r be the diagonal matrix containing its nonzero eigenvalues (in decreasing order of magnitude), and let \mathbf{Q}_r be the $n \times r$ matrix whose columns are the eigenvectors corresponding to the nonzero λ_j of \mathbf{A} . Then,

$$\mathbf{A}^{-1} = \mathbf{Q}_r \Lambda_r^{-1} \mathbf{Q}_r^T$$

Or this is the same as letting Λ^{-1} with $1/\lambda_j$ for $\lambda_j \neq 0$ and 0 for $\lambda_j = 0$.

$$= \underbrace{\mathbf{Q}_r \Lambda_r^{-1/2}}_{(\mathbf{A}^{1/2})^{-1}} \mathbf{Q}_r^T \underbrace{\mathbf{Q}_r \Lambda_r^{1/2}}_{(\mathbf{A}^{1/2})} = \dots$$

† The form of linear models is

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{e},$$

- ▶ \mathbf{y} : $n \times 1$ vector of observations (random)
- ▶ \mathbf{X} : $n \times p$ matrix of known constants (*design* matrix) with $r(\mathbf{X}) = r$
- ▶ $\boldsymbol{\beta}$: $p \times 1$ vector of unobservable parameters
- ▶ \mathbf{e} : $n \times 1$ vector of unobservable random errors

★ Assumptions (Gauss-Markov model assumption):

- ▶ $E(\mathbf{e}) = \mathbf{0}$ ($\Leftrightarrow E(\mathbf{y}) = \mathbf{X}\boldsymbol{\beta}$)
- ▶ $\text{Cov}(\mathbf{e}) = \sigma^2 I$ where σ^2 is some unknown parameter ($\sigma^2 > 0$)

\mathbf{Y} : $n \times 1$ random vector

$$E(\mathbf{Y}) = \begin{bmatrix} E(y_1) \\ \vdots \\ E(y_n) \end{bmatrix} = \boldsymbol{\mu}$$

$$\text{Cov}(\mathbf{Y}, \mathbf{Y}) = \text{Var}(\mathbf{Y}) = E \left(\begin{matrix} (\mathbf{Y} - \boldsymbol{\mu}) \\ n \times 1 \end{matrix} (\mathbf{Y} - \boldsymbol{\mu})^T \right)$$

$$\text{Cov}(\mathbf{Y}, \mathbf{W}) = E \left(\begin{matrix} (\mathbf{Y} - \boldsymbol{\mu}_Y) & n \times 1 \\ (\mathbf{W} - \boldsymbol{\mu}_W)^T & 1 \times n \end{matrix} \right)$$

♠ Remind!

- $E(\mathbf{a}^T \mathbf{y}) = \mathbf{a}^T E(\mathbf{y})$
- $\text{Cov}(\mathbf{A}^T \mathbf{y} + \mathbf{b}) = \mathbf{A}^T \text{Cov}(\mathbf{y}) \mathbf{A}$
- $\text{Var}(\mathbf{a}^T \mathbf{y}) = \mathbf{a}^T \text{Cov}(\mathbf{y}) \mathbf{a}$ for fixed \mathbf{a}
- $\text{Cov}(\mathbf{a}^T \mathbf{y}, \mathbf{c}^T \mathbf{y}) = \mathbf{a}^T \text{Cov}(\mathbf{y}) \mathbf{c}$ for fixed \mathbf{a} and \mathbf{c}
- $\text{Cov}(\mathbf{A}^T \mathbf{y}) = \mathbf{A}^T \text{Cov}(\mathbf{y}) \mathbf{A}$ for fixed \mathbf{A}

• $\text{Cov}(\mathbf{y})$ is nonnegative definite for any random vector \mathbf{y}

Claim: for arbitrary vector \mathbf{u} , $\mathbf{u}^T \text{Cov}(\mathbf{y}) \mathbf{u} \geq 0$

$$\mathbf{u}^T \text{Cov}(\mathbf{y}) \mathbf{u} = \mathbf{u}^T E \left((\mathbf{y} - \boldsymbol{\mu}) (\mathbf{y} - \boldsymbol{\mu})^T \right) \mathbf{u}$$

$$= E \left(\underbrace{\left(\frac{(\mathbf{y} - \boldsymbol{\mu})^T \mathbf{u}}{1 \times n} \right)^T}_{n \times 1} \underbrace{(\mathbf{y} - \boldsymbol{\mu})^T \mathbf{u}}_{1 \times n} \right)$$

$$= E(s^2) \geq 0$$

⊗

- \mathbf{Y} is nonsingular if $\text{Cov}(\mathbf{y})$ is nonsingular
- \mathbf{Y} is singular if $\text{Cov}(\mathbf{y})$ is singular

◇ Cor For a symmetric matrix \mathbf{A} , there exists \mathbf{A}^- such that $\mathbf{A}^- \mathbf{A} \mathbf{A}^- = \mathbf{A}^-$ and $(\mathbf{A}^-)^T = \mathbf{A}^-$.

$$\mathbf{A}^- = \mathbf{Q}_r \mathbf{\Lambda}_r^{-1} \mathbf{Q}_r^T$$

In layman's terms, there exists a reflexive ($\mathbf{A}^- \mathbf{A} \mathbf{A}^- = \mathbf{A}^-$), symmetric generalized inverse for any symmetric matrix \mathbf{A} .

$$E(\lambda^T \hat{\beta}) = \lambda^T \beta$$

$$= E(\lambda^T (X^T X)^{-} X^T y) = E(\lambda^T X (X^T X)^{-} X^T y)$$

$$= \underbrace{\lambda^T X (X^T X)^{-} X^T X}_{= X} \beta = \lambda^T X \beta = \underline{\underline{\lambda^T \beta}}$$

$$\bullet X G X^T X = X H X^T X = X$$

G & H are a g-inverse of $(X^T X)$

♠ Consider a linear model:

$$y = X\beta + e,$$

$$\lambda \in C(X^T)$$

$$\exists a \text{ s.t. } \lambda = X^T a$$

($\Leftrightarrow \lambda^T = a^T X$)

where $E(e) = \mathbf{0}$ and $\text{Var}(e) = \sigma^2 I$. Suppose $\lambda^T \beta$ is estimable. Find the variance of $\lambda^T \hat{\beta}$.

$$\text{Var}(\lambda^T \hat{\beta}) = \text{Var}(\lambda^T (X^T X)^{-} X^T y) = (\lambda^T (X^T X)^{-} X^T) \text{Var}(y)$$

$$(\lambda^T (X^T X)^{-} X^T)^T = \sigma^2 \lambda^T (X^T X)^{-} X^T X \underbrace{(X^T X)^{-}}_{(X^T X)^{-}} \lambda$$

$$= \underline{\underline{\sigma^2 \lambda^T (X^T X)^{-} \lambda}}$$

* Note: From Exercise 4.2, $\text{Var}(\lambda^T \hat{\beta})$ does not depend on the choice of g-inverse $(X^T X)^{-}$.

$$\begin{aligned} \text{Var}(d^T y) &\geq \text{Var}(d^T y - a^T P y) + \text{Var}(a^T P y) \\ &= \underbrace{\text{Var}(d^T y - \lambda^T \hat{\beta})}_{\geq 0} + \text{Var}(\lambda^T \hat{\beta}) \\ &\geq \text{Var}(\lambda^T \hat{\beta}) \end{aligned}$$

$$E(d^T y) = \lambda^T \beta$$

$$\Leftrightarrow d^T X \beta = \lambda^T \beta$$

$$\Leftrightarrow \underbrace{d^T X}_{\lambda^T} = \lambda^T = \underbrace{a^T X}$$

The Gauss-Markov Theorem

♣ Th 4.1: Under the assumptions of the Gauss-Markov model,

$$y = X\beta + e, \quad \text{where } E(e) = 0, \quad \text{Var}(e) = \sigma^2 I,$$

if $\lambda^T \beta$ is estimable, then $\lambda^T \hat{\beta}$ is the best (minimum variance) linear unbiased estimator (BLUE) of $\lambda^T \beta$, where $\hat{\beta}$ solves the NEs $X^T X \beta = X^T y$.

Suppose $d^T y$ is another unbiased estimator of $\lambda^T \beta$

Goal: want to show $\text{Var}(d^T y) \geq \text{Var}(\lambda^T \hat{\beta})$.

since $\lambda^T \beta$ is estimable, $\lambda \in C(X^T) \Leftrightarrow \exists a \text{ s.t. } \lambda = X^T a$
 $(\Leftrightarrow \lambda^T = a^T X)$

$$\lambda^T \hat{\beta} = \lambda^T (X^T X)^{-1} X^T y = \underbrace{a^T X (X^T X)^{-1} X^T}_= P y = a^T P y \quad \textcircled{*} = 0$$

$$\begin{aligned} \text{Var}(d^T y) &= \text{Var}(d^T y - a^T P y + a^T P y) \\ &= \underbrace{\text{Var}(d^T y - a^T P y)}_{\geq 0} + \text{Var}(a^T P y) + \underbrace{\text{Cov}(d^T y - a^T P y, a^T P y)}_{= 0} \\ &= (d^T - a^T P) y \quad \geq 0 \quad = \text{Var}(\lambda^T \hat{\beta}) = \sigma^2 I \end{aligned}$$

$$\textcircled{*} = \text{Cov}(d^T y - a^T P y, a^T P y) = (d^T - a^T P) \text{Var}(y) \textcircled{*} (a^T P)^T$$

$$= \sigma^2 (d^T - a^T P) P a = \sigma^2 \underbrace{(d^T P - a^T P)}_{= 0} a = 0$$

$$d^T P - a^T P = \underbrace{d^T X (X^T X)^{-1} X^T}_{= a^T X} - a^T X (X^T X)^{-1} X^T = 0$$

will show

$$\underline{r(\mathbf{x}) = \mathbf{r}}$$

♠ Let's consider multiple λ_j , $j = 1, \dots, m$ together. Let the columns λ_j of Λ ($p \times m$) where λ_j are linearly independent; then

• The LSE of $\Lambda^T \beta$ is $\Lambda^T \hat{\beta}$ (BLUE) $\Lambda^T = \begin{bmatrix} \lambda_1^T \\ \vdots \\ \lambda_m^T \end{bmatrix}$

• Its variance is

$$\begin{aligned} \text{Cov}(\Lambda^T \hat{\beta}) &= \text{Cov}(\Lambda^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}) \\ &= \sigma^2 \Lambda^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} (\mathbf{X}^T \mathbf{X})^{-1} \Lambda \\ &= \sigma^2 \Lambda^T (\mathbf{X}^T \mathbf{X})^{-1} \Lambda. \end{aligned}$$

For any unbiased estimator, $\mathbf{C}^T \mathbf{y}$,

$$\text{Cov}(\mathbf{C}^T \mathbf{y}) - \text{Cov}(\Lambda^T \hat{\beta}) \geq 0.$$

$\Rightarrow \Lambda^T \hat{\beta}$ is the BLUE.

$$\beta_0 = E(y) \text{ at } X=0$$

$$y_i = \beta_0 + \beta_1 x_i + e_i$$

$$\begin{aligned} \Leftrightarrow y_i &= \beta_0 + \beta_1(x_i - \bar{x} + \bar{x}) + e_i \\ &= \beta_0 + \bar{x}\beta_1 + \beta_1(x_i - \bar{x}) + e_i \\ &= \gamma_0 + \gamma_1 x_i^* + e_i \quad \leftarrow \end{aligned}$$

height vs weight
x y

$$\gamma_0 = E(y) \text{ at } X^* = 0 \Leftrightarrow x_i = \bar{x}$$

♠ Ex 1 Consider a simple linear regression model:

$$y_i = \beta_0 + \beta_1 x_i + e_i,$$

where $E(\mathbf{e}) = \mathbf{0}$ and $\text{Var}(\mathbf{e}) = \sigma^2 \mathbf{I}$. Find the variance of $\hat{\beta} = \begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix}$

$$\hat{\beta} = \Lambda^T \beta = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \beta \quad \hat{\beta} = \Lambda^T \hat{\beta} = \hat{\beta}$$

$$\begin{aligned} \text{Var}(\hat{\beta}) &= \sigma^2 \Lambda^T (X^T X)^{-1} \Lambda \\ &= \sigma^2 (X^T X)^{-1} \\ &= \sigma^2 \left(\begin{bmatrix} 1 & \dots & 1 \\ x_1 & \dots & x_n \end{bmatrix} \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \right)^{-1} \\ &= \sigma^2 \begin{bmatrix} n & \sum x_i \\ \sum x_i & \sum x_i^2 \end{bmatrix}^{-1} \\ &= \frac{\sigma^2}{n \sum x_i^2 - (\sum x_i)^2} \begin{bmatrix} \sum x_i^2 & -\sum x_i \\ -\sum x_i & n \end{bmatrix} \\ &= \frac{\sigma^2}{n \sum (x_i - \bar{x})^2} \begin{bmatrix} \sum x_i^2 & -\sum x_i \\ -\sum x_i & n \end{bmatrix} \\ &= \frac{\sigma^2}{S_{xx}} \begin{bmatrix} \sum x_i^2 & -\sum x_i \\ -\sum x_i & n \end{bmatrix} \end{aligned}$$

$\text{Var}(\hat{\beta})$ 0

\circ Lemma 4.1 Let \mathbf{Z} be a vector random variable with $E(\mathbf{Z}) = \boldsymbol{\mu}$ and $\text{Cov}(\mathbf{Z}) = \boldsymbol{\Sigma}$. Then $E(\mathbf{Z}^T \mathbf{A} \mathbf{Z}) = \boldsymbol{\mu}^T \mathbf{A} \boldsymbol{\mu} + \text{tr}(\mathbf{A} \boldsymbol{\Sigma})$.

- The Aitken Model and Generalized Least Squares (GLS)

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{e}, \quad \text{where } E(\mathbf{e}) = \mathbf{0}, \quad \text{Var}(\mathbf{e}) = \sigma^2\mathbf{V}.$$

Here we assume \mathbf{V} is a known positive definite matrix.

♣ What is coming next?

◇ Let's find an estimator (generalized least square estimator) for an estimable function, $\boldsymbol{\lambda}^T \boldsymbol{\beta}$, $\boldsymbol{\lambda}^T \hat{\boldsymbol{\beta}}_{GLS}$.

◇ Then we will show it is the BLUE for $\boldsymbol{\lambda}^T \boldsymbol{\beta}$.

- Recall the Aitken model,

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{e}, \quad \text{where } E(\mathbf{e}) = \mathbf{0}, \quad \text{Var}(\mathbf{e}) = \sigma^2\mathbf{V}. \quad (2)$$

Here we assume \mathbf{V} is a known positive definite matrix. We can write $\mathbf{V}^{-1} = \mathbf{R}\mathbf{R}^T$ for some nonsingular matrix \mathbf{R} .

$$\mathbf{V} = \mathbf{R}^{-1}(\mathbf{R}^T)^{-1}$$

In particular, consider $\mathbf{V} = \mathbf{Q}\boldsymbol{\Lambda}\mathbf{Q}^T$ and let $\mathbf{R} = \mathbf{Q}\boldsymbol{\Lambda}^{-1/2}\mathbf{Q}^T$ (square root matrix, symmetric & nonsingular).

- How \mathbf{V} works?

Minimizes

$$(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^T \mathbf{V}^{-1} (\mathbf{y} - \mathbf{X}\boldsymbol{\beta}).$$

In words, instead of minimizing the squared distance between \mathbf{y} and $\mathbf{X}\boldsymbol{\beta}$, we minimize a generalized distance determined by \mathbf{V}^{-1} .

★: Ex Consider a simple linear regression and \mathbf{V} diagonal matrix. Observe

$$(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^T \mathbf{V}^{-1} (\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) = \sum_i \left(\frac{1}{V_{ii}} (y_i - \beta_0 - \beta_1 x_i)^2 \right)$$

(Known as weighted least squares!)

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} + \begin{bmatrix} e_1 \\ \vdots \\ e_n \end{bmatrix}$$

$$\begin{aligned} \text{Var}(e_i) &= \sigma^2 V_{ii} \\ \text{Cov}(e_i, e_{i'}) &= 0 \end{aligned}$$

$$\begin{bmatrix} y_1 - \beta_0 - \beta_1 x_1 \\ \vdots \\ y_n - \beta_0 - \beta_1 x_n \end{bmatrix}^T \begin{bmatrix} \frac{1}{V_{11}} & & & \\ & \frac{1}{V_{22}} & & \\ & & \ddots & \\ & & & \frac{1}{V_{nn}} \end{bmatrix} \begin{bmatrix} y_1 - \beta_0 - \beta_1 x_1 \\ \vdots \\ y_n - \beta_0 - \beta_1 x_n \end{bmatrix} \quad \text{29/33}$$